

# **An effective tree data structure in Fast Multipole Method**

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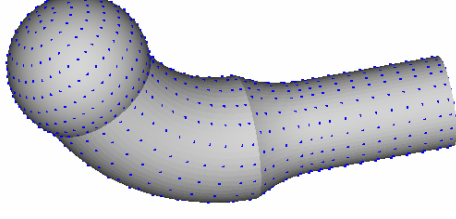
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# Hybrid BNM

## ➤ Main features:

- Combines a modified functional with the *Moving Least Squares* (MLS) approximation
- Three independent variables
  - internal temperature
  - boundary temperature
  - boundary normal flux



Example of meshless discretization

## ➤ Variables approximation

- Domain variables
- Boundary variables

$$\phi = \sum_{I=1}^N \phi_I^s x_I$$

$$\phi_I^s = \frac{1}{\kappa} \frac{1}{4\pi r(Q, \mathbf{s}_I)}$$

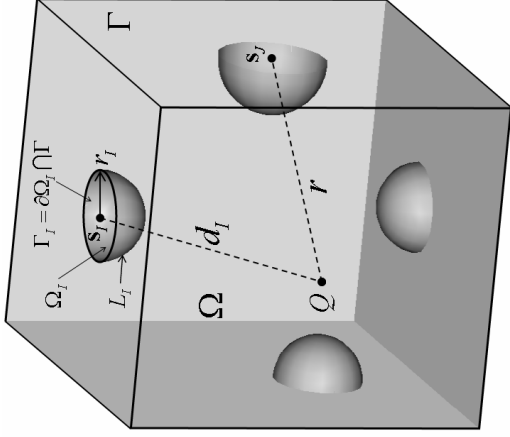
$$\tilde{\phi}(\mathbf{s}) = \sum_{I=1}^N \Phi_I(\mathbf{s}) \hat{\phi}_I$$

$$\tilde{q}(\mathbf{s}) = \sum_{I=1}^N \Phi_I(\mathbf{s}) \hat{q}_I$$



# Hybrid BNM (2)

## ➤ System of equations



$$\mathbf{U}\mathbf{x} = \mathbf{H}\hat{\mathbf{q}}$$

$$U_{IJ} = \int_{\Gamma_s^J} \phi_I^s v_J(Q) d\Gamma$$

$$V_{IJ} = \int_{\Gamma_s^J} q_I^s v_J(Q) d\Gamma$$

$$\mathbf{V}\mathbf{x} = \mathbf{H}\hat{\phi}$$

$$H_{IJ} = \int_{\Gamma_s^J} \Phi_I(\mathbf{s}) v_J(Q) d\Gamma$$

- Three purposes of elements in BEM:
  - To interpolate Boundary variables
  - To facilitate boundary integration
  - To approximate the geometry



# Iterative solver

## ➤ Matrix-vector multiplication

$$x_I'^{k+1} = \sum_{J=1}^N \int_{\Gamma_I} \phi_J^s v_I(Q) x_J^k d\Gamma$$

$$x_I'^{k+1} = \sum_{J=1}^N \int_{\Gamma_I} \frac{\partial \phi_J^s}{\partial n} v_I(Q) x_J^k d\Gamma$$

**Complexity of an iterative solver:**

**Memory:  $O(N^2)$       CPU time:  $O(N^2)$**

**Fast Multipole Method (FMM):**

**Reducing computational complexity to  $O(N)$**

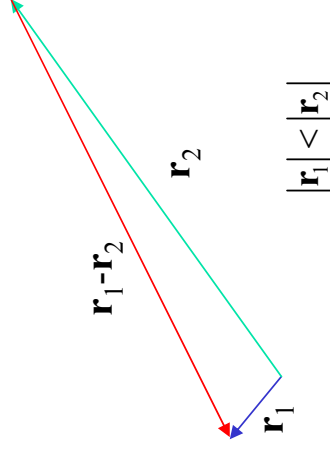


# Addition theorems

## ➤ First addition theorem

Let  $\mathbf{r}_1$  and  $\mathbf{r}_2$  be two vectors with spherical coordinates  $(r_1, \alpha_1, \beta_1)$  and  $(r_2, \alpha_2, \beta_2)$ , respectively. It follows

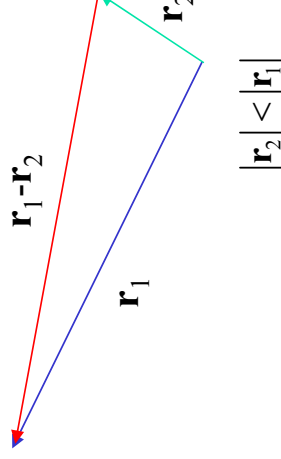
$$\frac{1}{|\mathbf{r}_1 - \mathbf{r}_2|} = \begin{cases} \sum_{n=0}^{\infty} \sum_{m=-n}^n R_n^m(\mathbf{r}_1) \overline{S_n^m(\mathbf{r}_2)}, & |\mathbf{r}_1| < |\mathbf{r}_2| \\ \sum_{n=0}^{\infty} \sum_{m=-n}^n R_n^m(\mathbf{r}_2) \overline{S_n^m(\mathbf{r}_1)}, & |\mathbf{r}_1| > |\mathbf{r}_2| \end{cases}$$



where

$$R_n^m(\mathbf{r}) = \frac{1}{(n+m)!} P_n^m(\cos \alpha) e^{im\beta} r^n$$

$$S_n^m(\mathbf{r}) = (n-m)! P_n^m(\cos \alpha) e^{im\beta} \frac{1}{r^{n+1}}$$



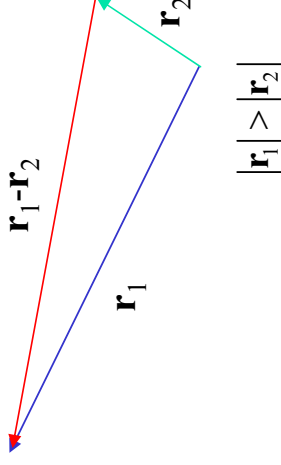


# Addition theorems (2)

## ➤ Second addition theorem

Let  $\mathbf{r}_1$  and  $\mathbf{r}_2$  be two vectors such that  $|\mathbf{r}_1| > |\mathbf{r}_2|$ , then

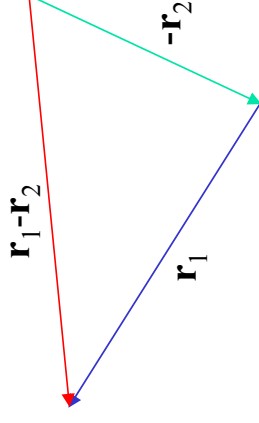
$$S_n^m(\mathbf{r}_1 - \mathbf{r}_2) = \sum_{n'=0}^{\infty} \sum_{m'=-n'}^{n'} \overline{R_{n'}^{m'}(\mathbf{r}_2)} S_{n+n'}^{m+m'}(\mathbf{r}_1)$$



## ➤ Third addition theorem

Let  $\mathbf{r}_1$  and  $\mathbf{r}_2$  be two arbitrary vectors, then

$$R_n^m(\mathbf{r}_1 - \mathbf{r}_2) = \sum_{n'=0}^n \sum_{m'=-n'}^{n'} R_{n'}^{m'}(-\mathbf{r}_2) R_{n-n'}^{m-m'}(\mathbf{r}_1)$$

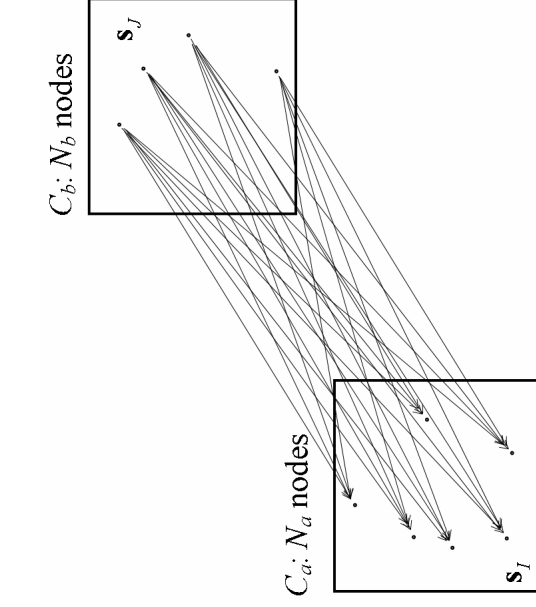




# Fast multipole

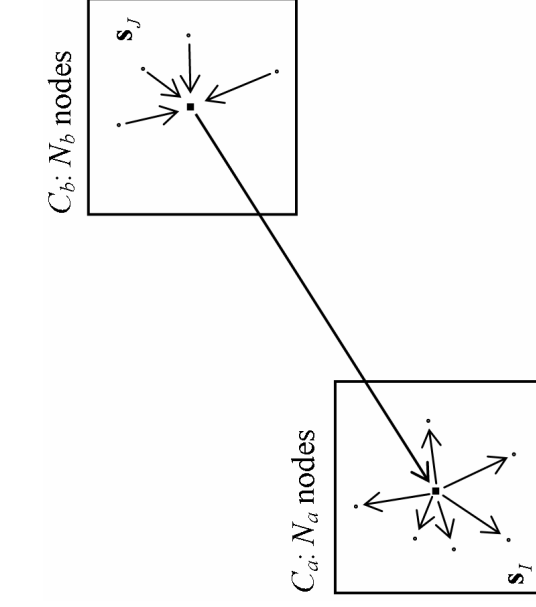
## ➤ Ideas of FMM

**Node-node interactions**



**Complexity  $O(N_a N_b)$**

**Cell-cell interactions**



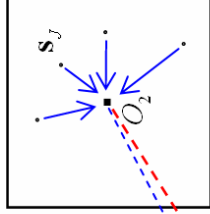
**Complexity  $O(N_a + N_b)$**



# Fast multipole (2)

## ➤ Multipole expansion

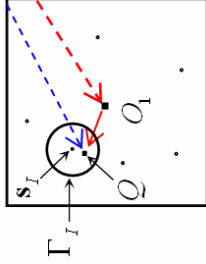
$C_b$ :  $N_b$  nodes



$$\phi_J^s = \frac{1}{4\pi K} \frac{1}{r(Q, \mathbf{s}_J)} = \frac{1}{4\pi K} \sum_{n=0}^{\infty} \sum_{m=-n}^n \overline{S_n^m(O_2 Q)} \overline{R_n^m(O_2 \mathbf{s}_J)}$$

for  $|\overline{O_2 Q}| > |\overline{O_2 \mathbf{s}_J}|$

$C_a$ :  $N_a$  nodes



$$\sum_{J=1}^{N_b} \int_{\Gamma_I} \phi_J^s v_I(Q) x'_J d\Gamma = \sum_{n=0}^{\infty} \sum_{m=-n}^n \int_{\Gamma_I} \frac{1}{4\pi K} \overline{S_n^m(O_2 Q)} v_I(Q) d\Gamma \overline{M_n^m(O_2)}$$

where

$$\overline{M_n^m(O_2)} = \sum_{J=1}^{N_b} \overline{R_n^m(O_2 \mathbf{s}_J)} x'_J$$

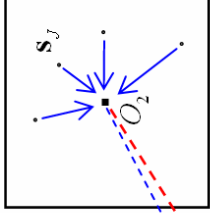




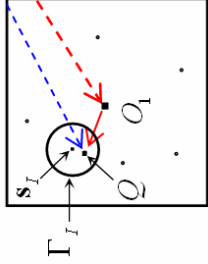
# Fast multipole (3)

## ➤ Local expansion

$C_b: N_b$  nodes



$C_a: N_a$  nodes



$$\overline{S_n^m(O_2 Q)} = \sum_{n'=0}^{\infty} \sum_{m'=-n'}^{n'} (-1)^{n'} R_{n'}^{m'}(\overline{O_1 Q}) \overline{S_{n+n'}^{m+m'}(O_1 O_2)}$$

for  $|\overline{O_1 O_2}| > |\overline{O_1 Q}|$

$$\sum_{J=1}^{N_b} \int_{\Gamma_I} \phi_J^s v_I(Q) x'_j d\Gamma = \sum_{n'=0}^{\infty} \sum_{m'=-n'}^{n'} \int_{\Gamma_I} \frac{1}{4\pi K} R_{n'}^{m'}(\overline{O_1 Q}) v_I(Q) d\Gamma L_n^{m'}(O_1)$$

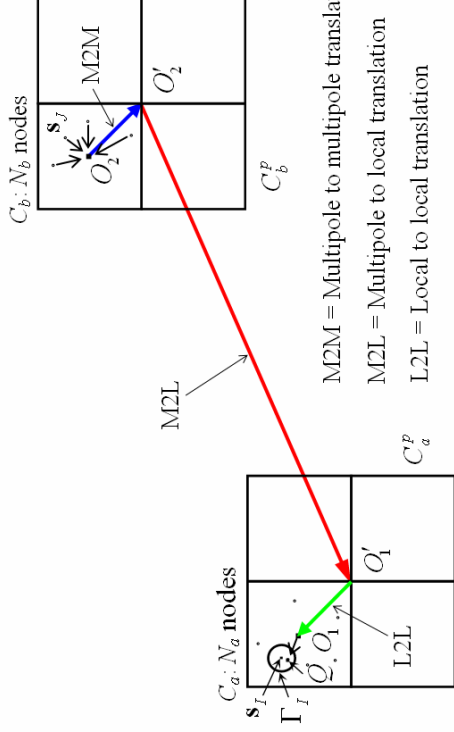
where

$$L_n^{m'}(O_1) = \sum_{n=0}^{\infty} \sum_{m=-n}^n (-1)^{n'} \overline{S_{n+n'}^{m+m'}(O_1 O_2)} M_n^m(Q_2)$$



# Fast multipole (4)

## ► Translation operators



$$M_{n'}^{m'}(Q_2') = \sum_{n=0}^{\infty} \sum_{m=-n}^n R_n^m(\overline{O_2'O_2}) M_{n-n'}^{m-m'}(Q_2)$$

Multipole to multipole translation

$$L_n^m(O_1') = \sum_{n'=0}^{\infty} \sum_{m'=-n'}^{n'} (-1)^n \overline{S_{n+n'}^{m-m'}}(\overline{O_1'O_2'}) M_{n'}^{m'}(Q_2')$$

Multipole to local translation

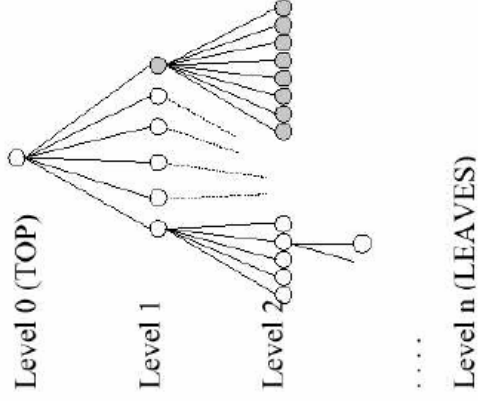
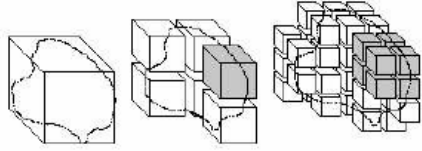
$$L_{n'}^{m'}(O_1) = \sum_{n=0}^{\infty} \sum_{m=-n}^n R_{n-n'}^{m-m'}(\overline{O_1'O_1}) L_n^m(Q_1)$$

Local to local translation



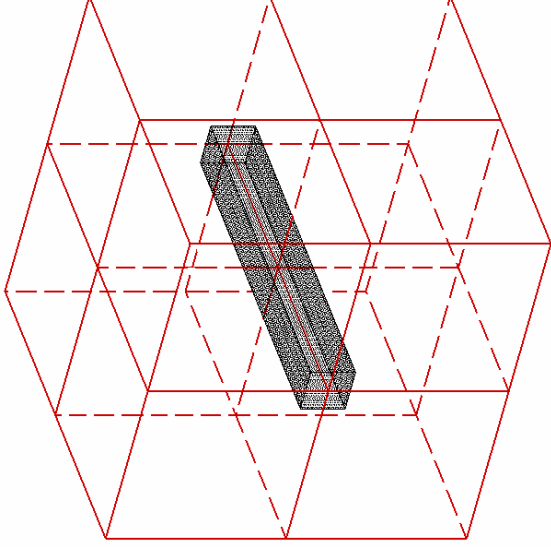
# Standard oct-tree

➤ **Algorithm**



➤ **Shortcoming**

**Does not reflect the geometry  
of the computational domain!**



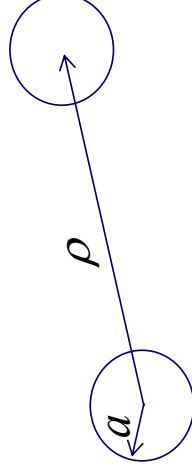
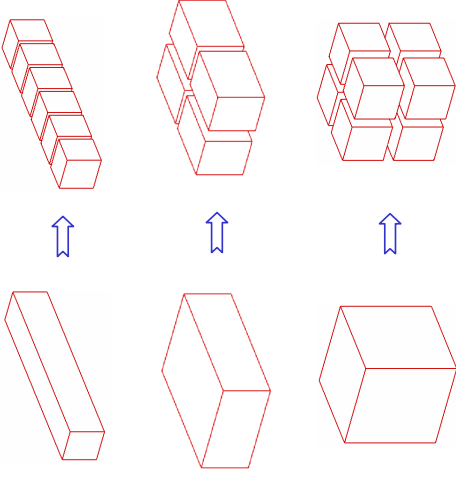


# Adaptive tree

➤ **Differs from the standard tree:**

- Use rectangular boxes instead of cubes
- Subdivide a box according to the shape of the box
- Tighten the child boxes at each subdivision step
- Generalize the Downward Pass algorithm, allowing M2L among the child boxes of a single parent box
- Determine the number of expansion terms in M2L by

$$p = 0.117 p_{norm} / \log\left(\frac{a}{\rho - a}\right)$$





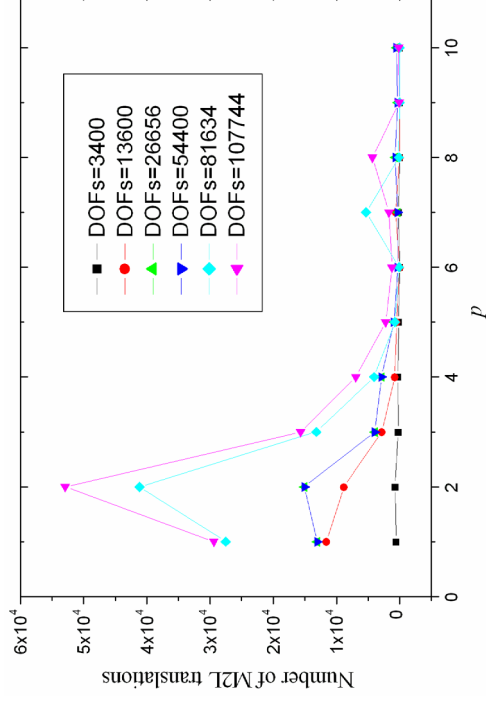
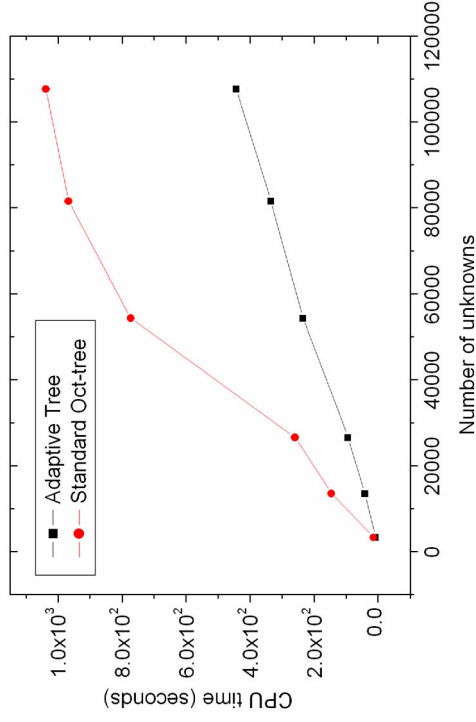
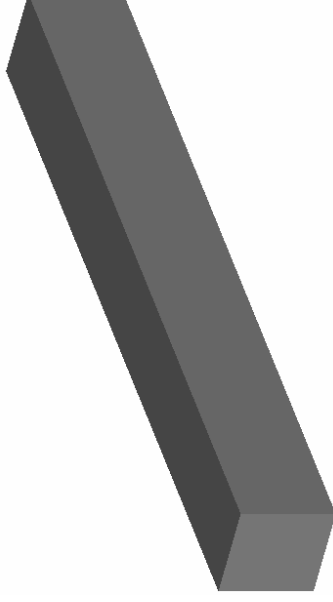
# Test problems

## ➤ A slender box

Dimensions:  $20 \times 20 \times 160$

Maximum nodes in a leaf: 60

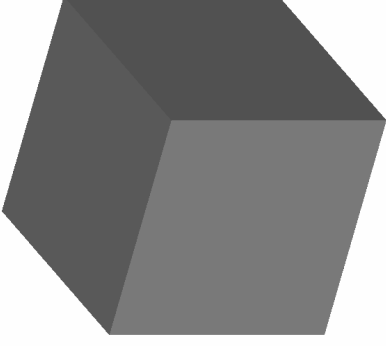
Number of expansion terms:  $p = 10$





# Test problems (2)

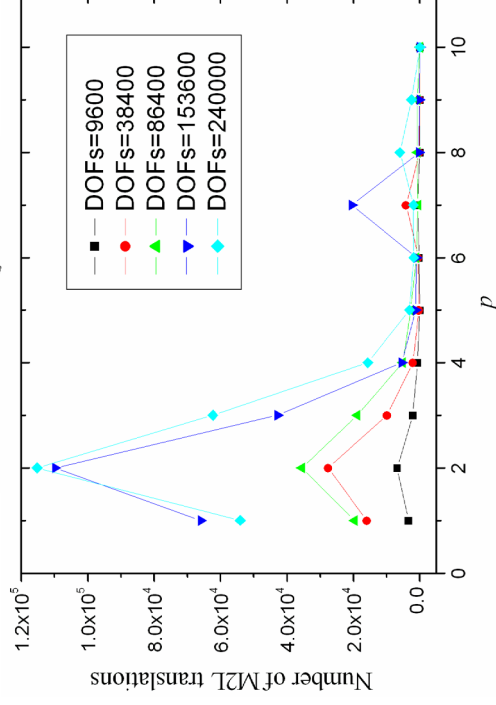
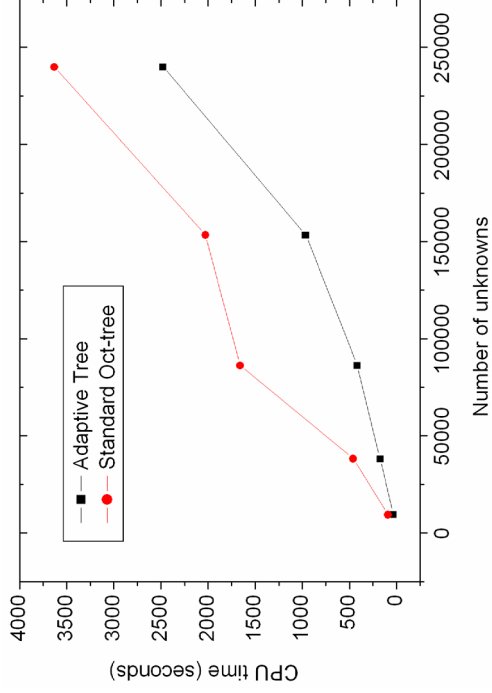
## ➤ A cube



Dimensions: Side length=2

Maximum nodes in a leaf: 60

Number of expansion terms:  $p = 10$





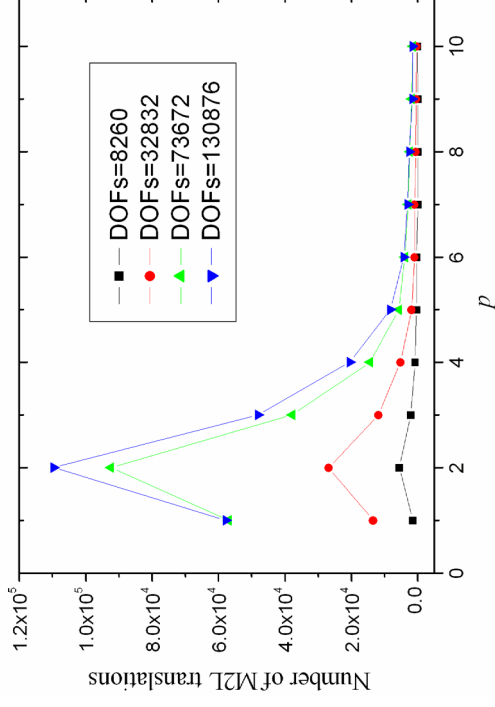
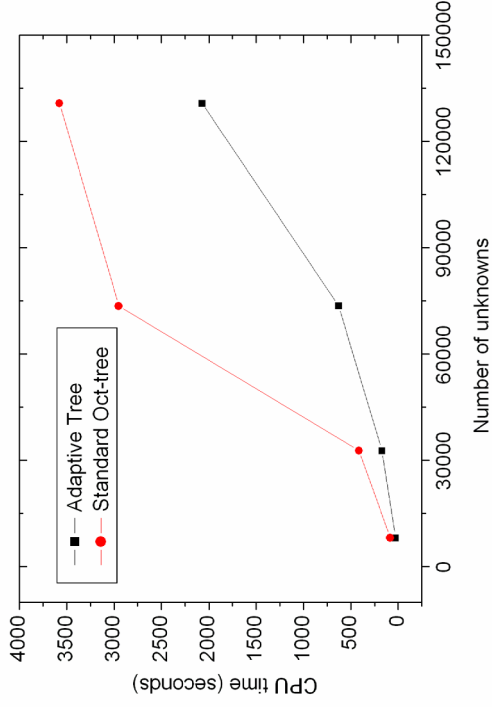
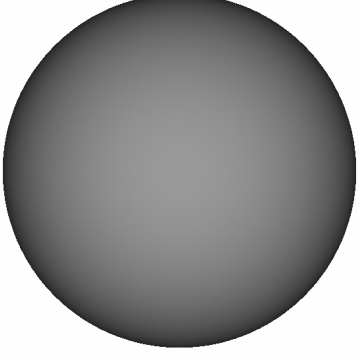
# Test problems (3)

## ➤ A sphere

Dimensions: Radius=5

Maximum nodes in a leaf: 60

Number of expansion terms:  $p=10$





## Conclusion remarks

- An adaptive tree data structure has been proposed. The new tree data structure is more flexible in matching the geometry (global and local) of the computational domain.
- Moreover, an adaptive value for the number of terms of the truncated series for M2L translations is used. This value is determined by the distance between the two interacting cells.
- Numerical examples show that the adaptive algorithm leads to trees with more compact cells and shallow depth, and runs significantly faster than the standard oct-tree.